## AMENDMENTS TO THE CLAIMS:

Replace the claims with the following rewritten listing:

1. (Currently Amended) A hand truck for transporting a load, the hand truck comprising a sub- frame with a foot portion extending therefrom so that the sub-frame is able to support the load, a main frame engaged with the sub-frame such that the sub-frame is able to be extended and retracted with respect to a lower end of the main frame, at least one wheel secured relative to the main frame so that the truck is able to be wheeled about, a motor, a controller coupled to the motor for enabling a user to control the operation of the motor, and a flexible linkage coupling the motor, main frame andrelative to the sub-frame together-such that the motor is operable to move the linkage to thereby extend or and retract the sub-frame so that the foot portion is configured for both a lowering and an elevating relative to said wheel,

wherein one end of the flexible linkage is secured relative to the sub-frame, and another end of the linkage is also secured relative to the sub-frame.

- 2. (Original) The hand truck of claim 1, wherein the sub-frame includes a pair of side rails and at least one cross member extending between the side rails.
- 3. (Previously Presented) The hand truck of claim 1, wherein the sub-frame includes an extension which is selectively extendable relative to the rest of the sub-frame to thereby lengthen the sub-frame.
- 4. (Original) The hand truck of claim 1, wherein the main frame includes a pair of side rails and at least one cross member extending between the side rails.
- 5. (Original) The hand truck of claim 1, wherein the main frame includes a handle.
- (Original) The hand truck of claim1, wherein the sub-frame is telescopically received by the main frame.

- 7. (Original) The hand truck of claim 1 further comprising selectively engagable wheel brakes for inhibiting rotation of the wheels.
- 8. (Original) The hand truck of claim 1, wherein the motor is an electric motor.
- (Currently Amended) The hand truck of claim 1 further-includingwherein the motor includes a gearbox which is driven by the motor.
- 10. (Original) The hand truck of claim 1, wherein the controller is a switch.
- 11. (Original) The hand truck of claim 1, wherein the flexible linkage is a roller chain.
- 12-13. (Cancelled)
- 14. (Currently Amended) The hand truck of claim 12, wherein the flexible linkage is trained around a rotatable member which is driven either directly or indirectly by the motor, and is also trained around another rotatable member secured relative to the main frame.
- 15. (Cancelled).
- 16. (Original) The hand truck of claim 14, wherein each rotatable member is a sprocket or an idler pulley.
- 17. (Original) The hand truck of claim 1 further comprising a spring which is secured to the sub-frame and the flexible linkage so as to take up slack in the flexible linkage.
- 18. (Original) The hand truck of claim 1 further comprising safety switches that are operable to control the motor to prevent excessive extension or retraction of the subframe.

- 19. (Original) The hand truck of claim 1 further including a weight sensor for sensing if the weight of the load carried by the truck is excessive.
- 20. (Original) The hand truck of claim 19 further including a safety switch operable by the weight sensor to prevent the motor from retracting and extending the sub-frame if the weight sensor senses that the weight of the load is excessive.